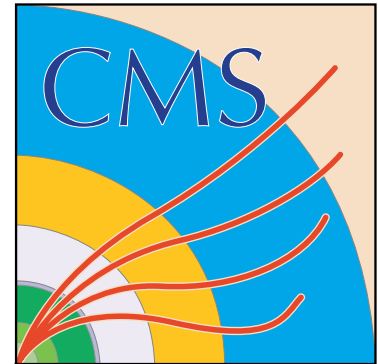


# Tracking and Vertexing at CMS



Steve Wagner

University of Colorado, Boulder



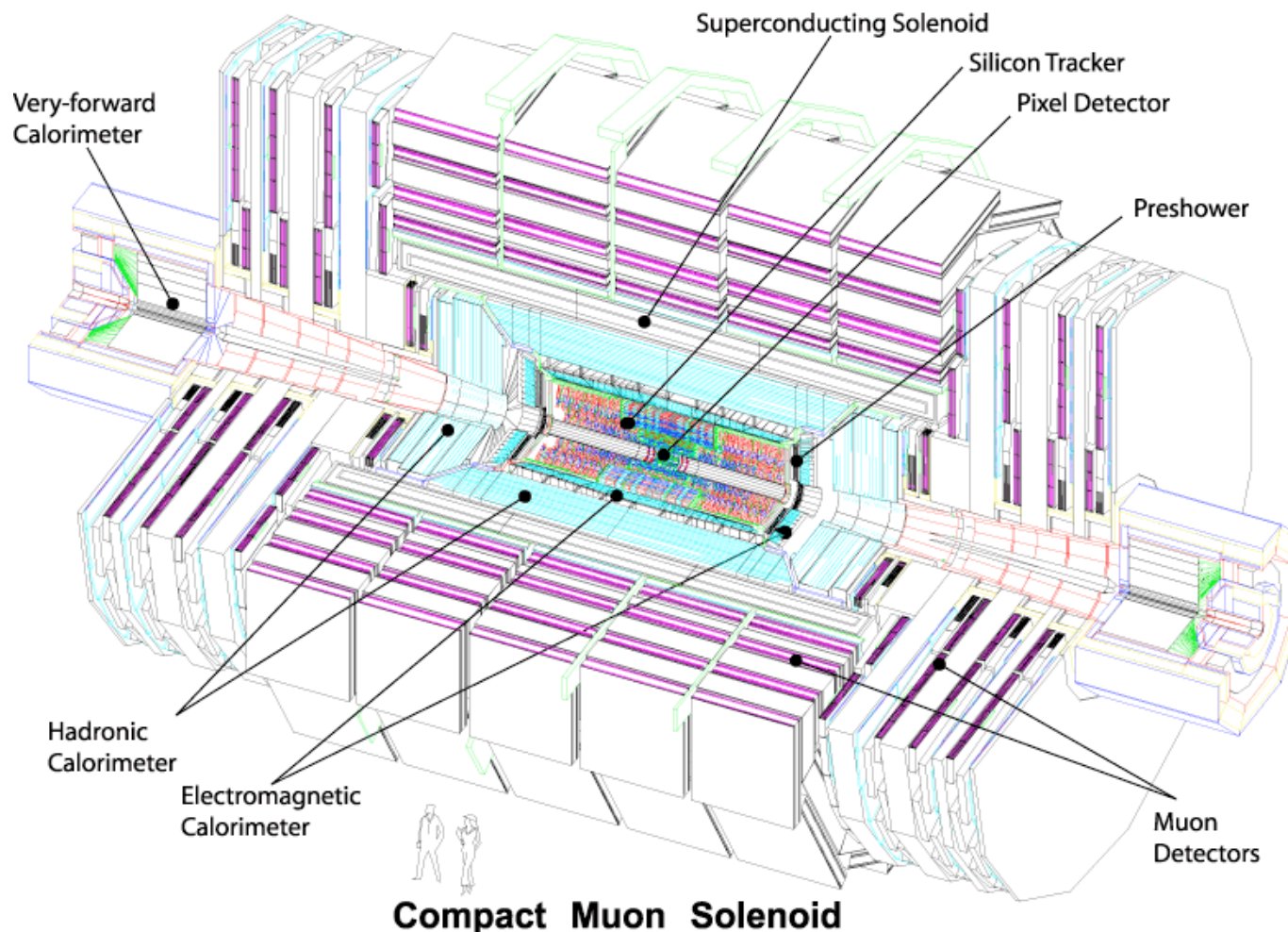
Hadron Collider Physics Symposium 2006  
26 May 2006

Additional information in:

- 6 - CMS detector status and commissioning
- 45 - Electron and Photon ID at ATLAS and CMS
- 46 - Muon ID at ATLAS and CMS
- 47 - Tau ID at ATLAS and CMS

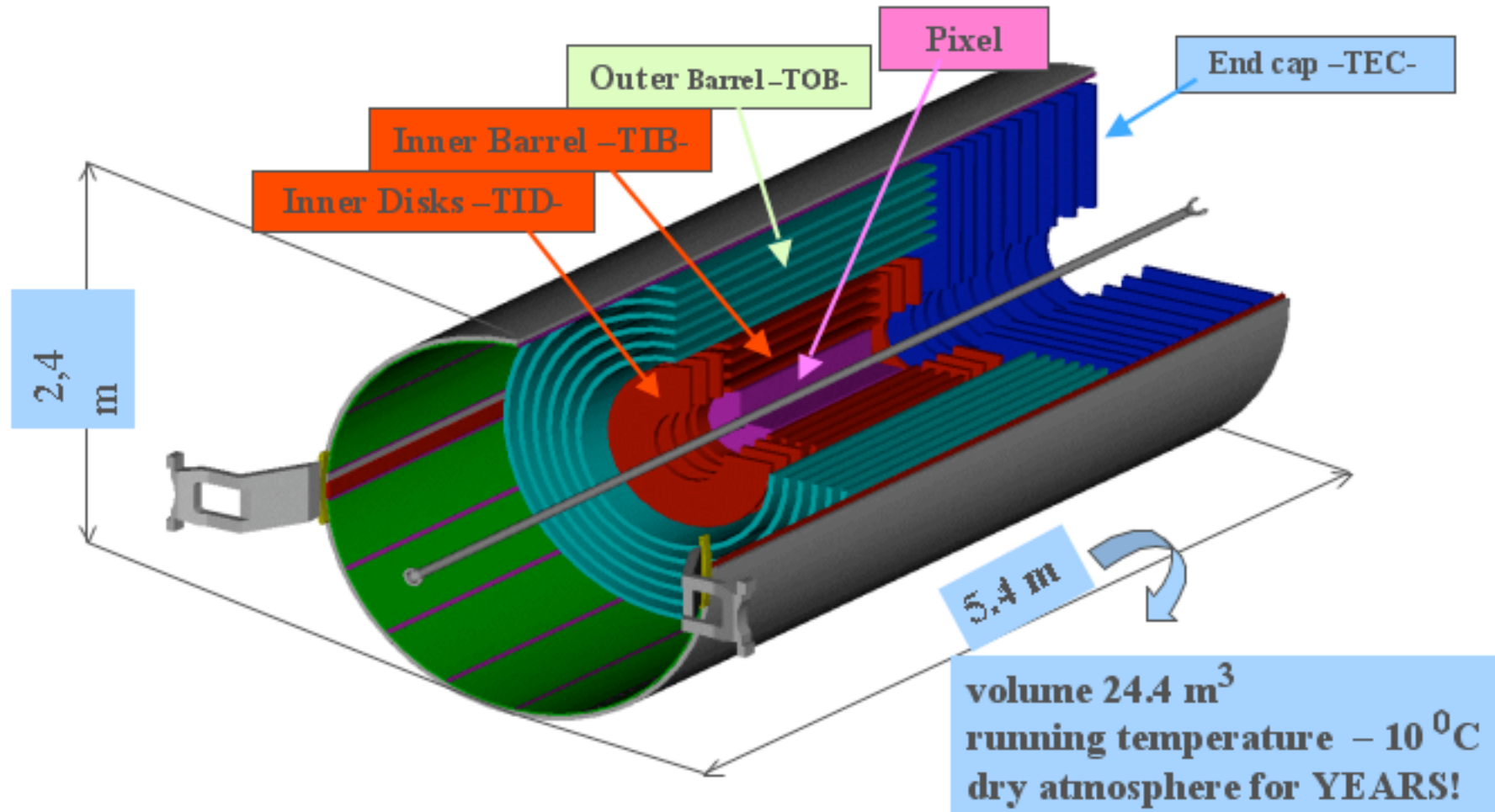
# The CMS Detector

- Inner tracking detectors small, colorful region of drawing below
- Shares 4 Tesla solenoid field (2.7 T!) with electromagnetic and hadronic calorimeters -> outer tracking layer at  $r \sim 110$  cm
- 1.9 mm sagitta for  $p_T = 100$  GeV/c tracks ( $190\mu$  for 1 TeV/c)

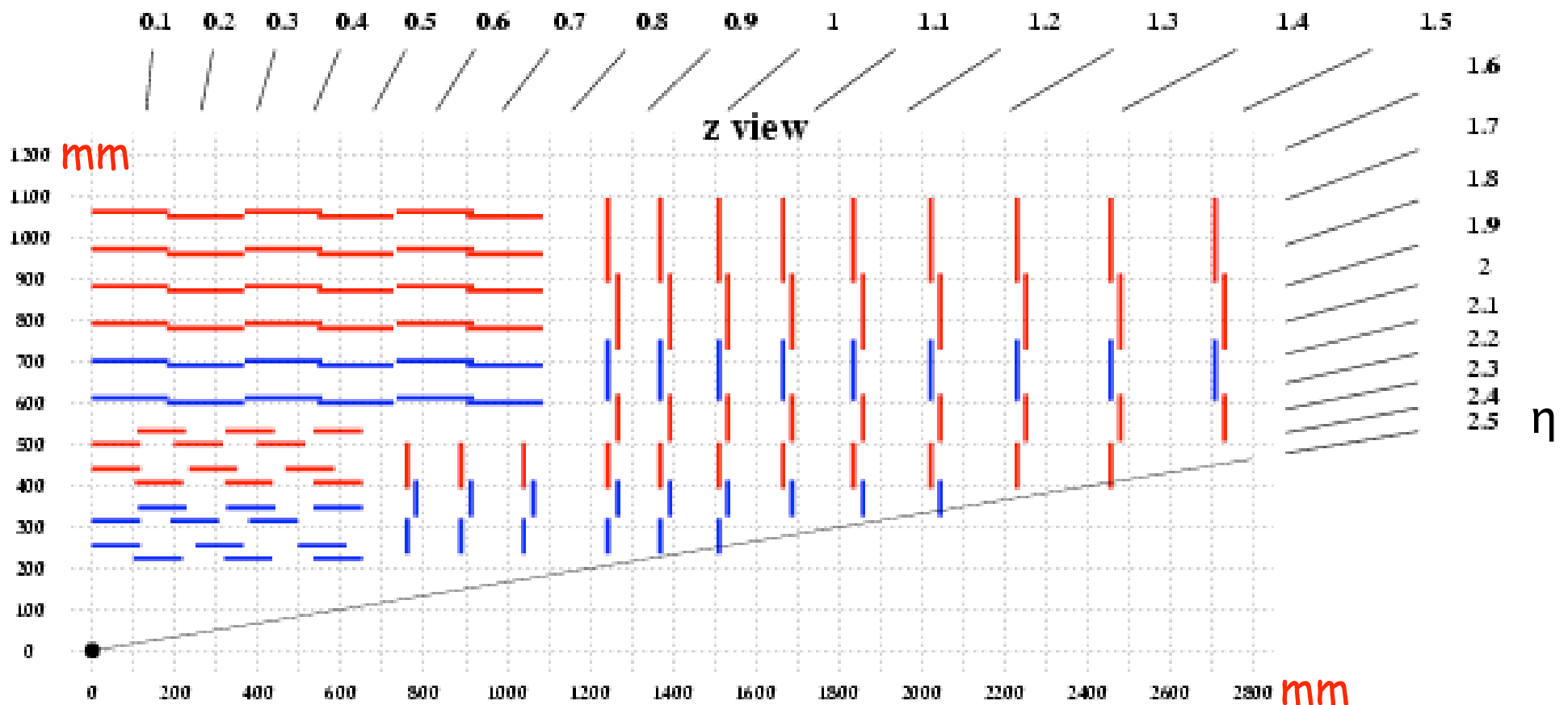


# The CMS Tracking Detectors

- At design L ( $10^{34} \text{ cm}^{-2}\text{s}^{-1}$ ) have 20 min-bias events/(25 ns bunch x-ing)
- $N/(25 \text{ ns} \times \text{cm}^2) \sim 5$  at  $r = 4.4 \text{ cm}$  (need pixels),  $\sim 0.1$  at  $r = 25 \text{ cm}$  (strips OK).  
Need fast response time
- Extreme radiation environment  $\rightarrow$  design for bulk type inversion and keep cold. Pixel and strip assemblies all have  $\text{C}_6\text{F}_{14}$  cooling loops



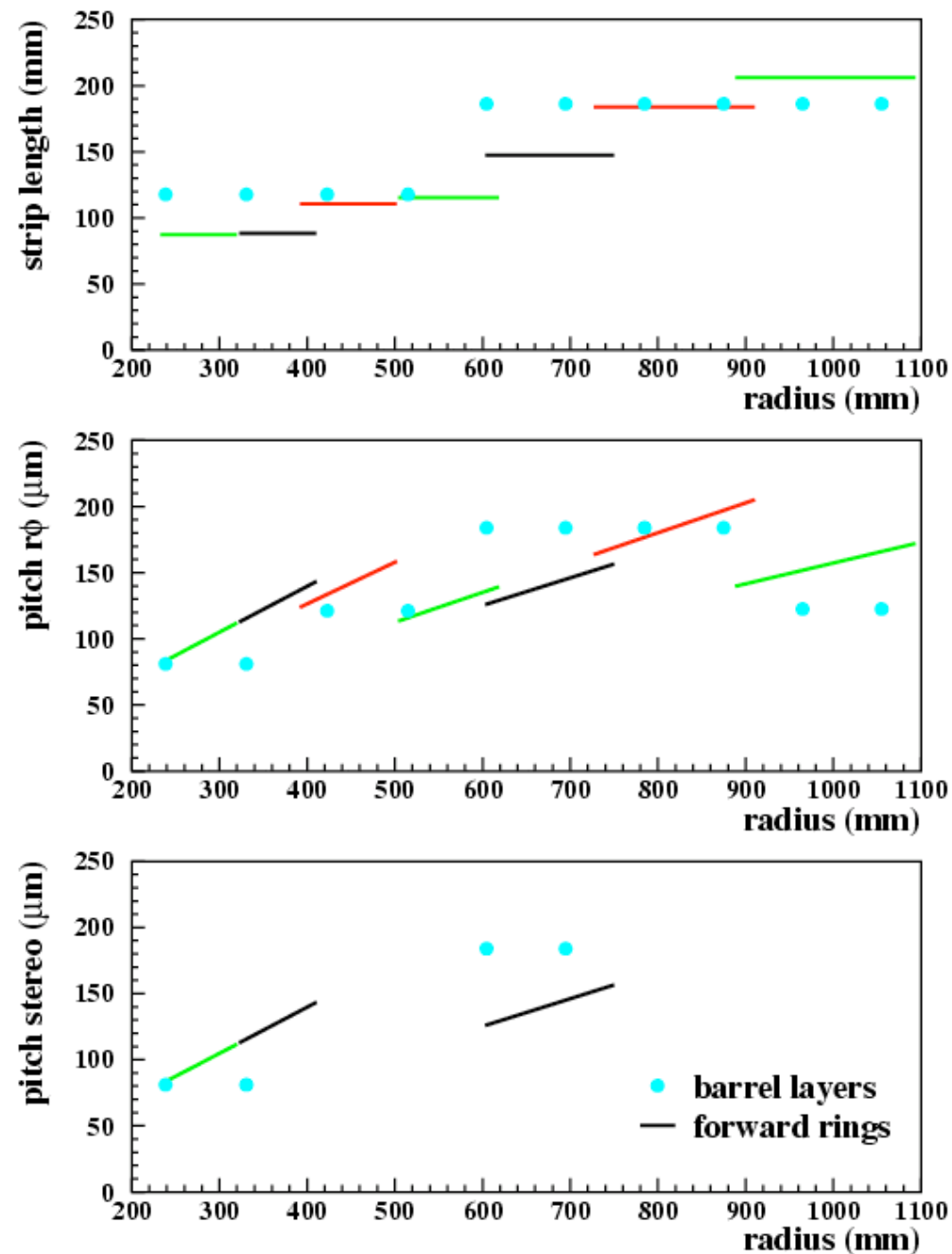
# The CMS Si Strip Trackers



- Red are single-sided (axial, radial) sensor modules
- Blue are double-sided (glued single-sided with small stereo angle)
- 440 m<sup>2</sup> of Si wafer, 210 m<sup>2</sup> covered with sensor, 10M channels. All ~16000 modules finished May 2006

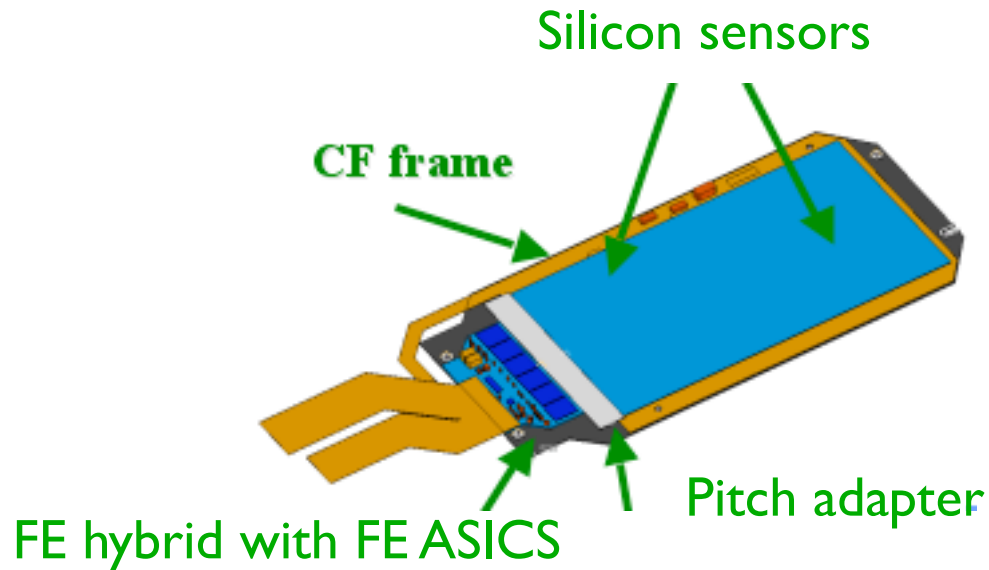
# Strip Tracker Layout

- Keep it reliable - single-sided, AC coupled, polysilicon biased
- Thin (320  $\mu\text{m}$ ) sensors for  $r < 60$  cm, thick (500  $\mu\text{m}$ ) sensors for  $r > 60$  cm
- $\langle 100 \rangle$  crystal less sensitive to radiation damage than  $\langle 111 \rangle$
- Keep width/pitch low ( $\sim 0.25$ ),  $\sim$ constant for low capacitance, independent of pitch and thickness
- After irradiation, expect  $S/N \sim 13$  for thin,  $\sim 15$  for thick sensors





# Barrel Strip Trackers (TIB, TOB)

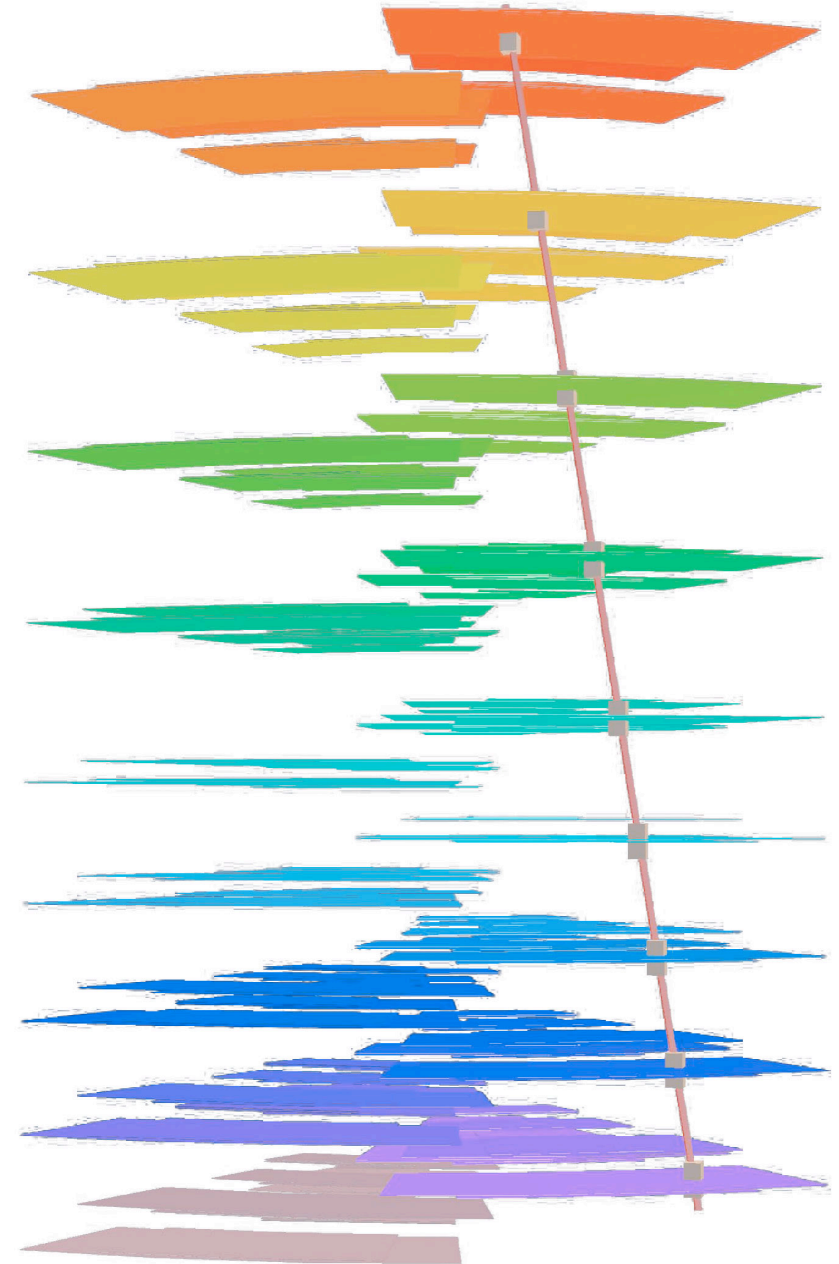


- Strips read out by APV ASIC (75376 total) connected thru a glass pitch adapter
- APV has peak (one sample) and 3 sample (for beam x-ing info) modes
- TIB modules, TOB RODs held in place by CF support structures
- Photo left is an early production ROD of double-sided modules in fixture



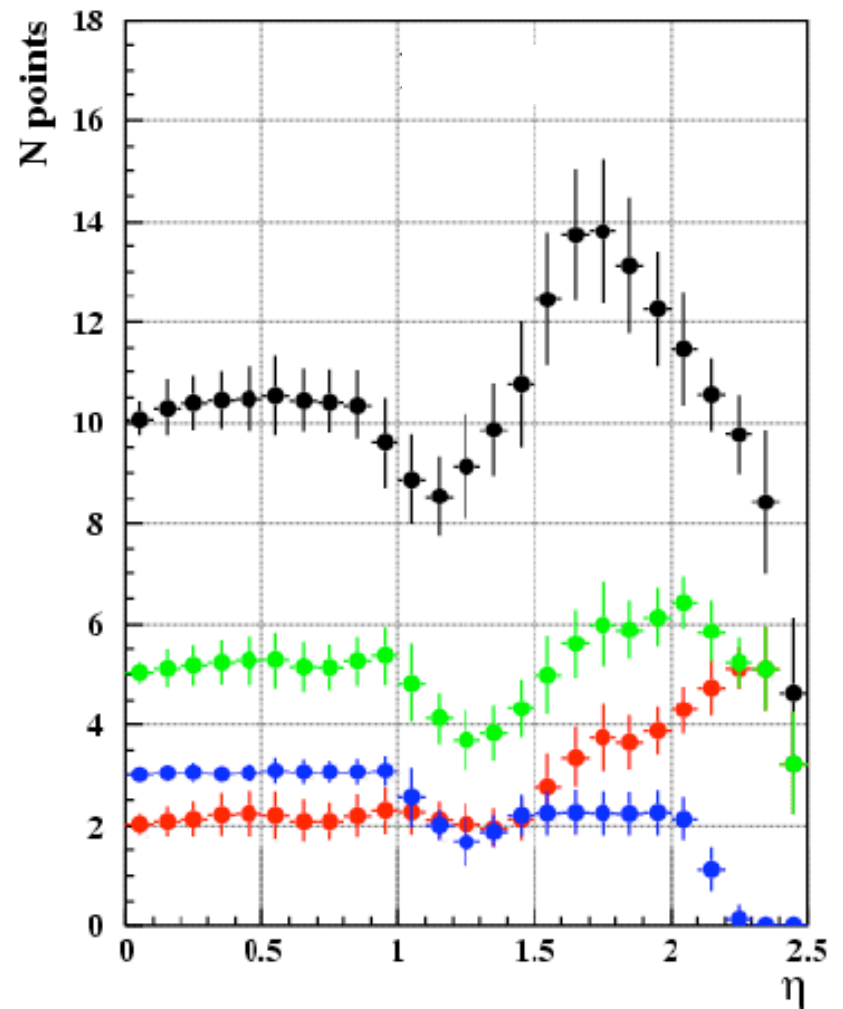
# Disk Strip Trackers (TID, TEC)

- Sensors, modules taper as they go out in r. Strips are either radial or small angle to radial
- TEC modules are arranged in petals, 16 of which make up a disk
- The tracker passed an important milestone in March 2006 when the first cosmic muon track was observed in the TEC+
- A total of 400 silicon strip modules were read out with a channel inefficiency of below 1% and a common mode noise of only 25% of the intrinsic noise.



# Strip-only Tracking

- For LHC 2007 commissioning run, Si strip trackers will be the only complete tracking system (very limited pixel arrays for commissioning only)
- But strips have  $\geq 7$  hit coverage to  $\eta \sim 2.4$
- Pixel-less tracking algorithms are currently being developed and adapted from existing ones
- 190 GeV  $H \rightarrow ZZ$  ( $Z \rightarrow \mu\mu$ ) signal is  $\sim 50\%$  wider without pixels than with (this can be reduced with a vertex constraint)

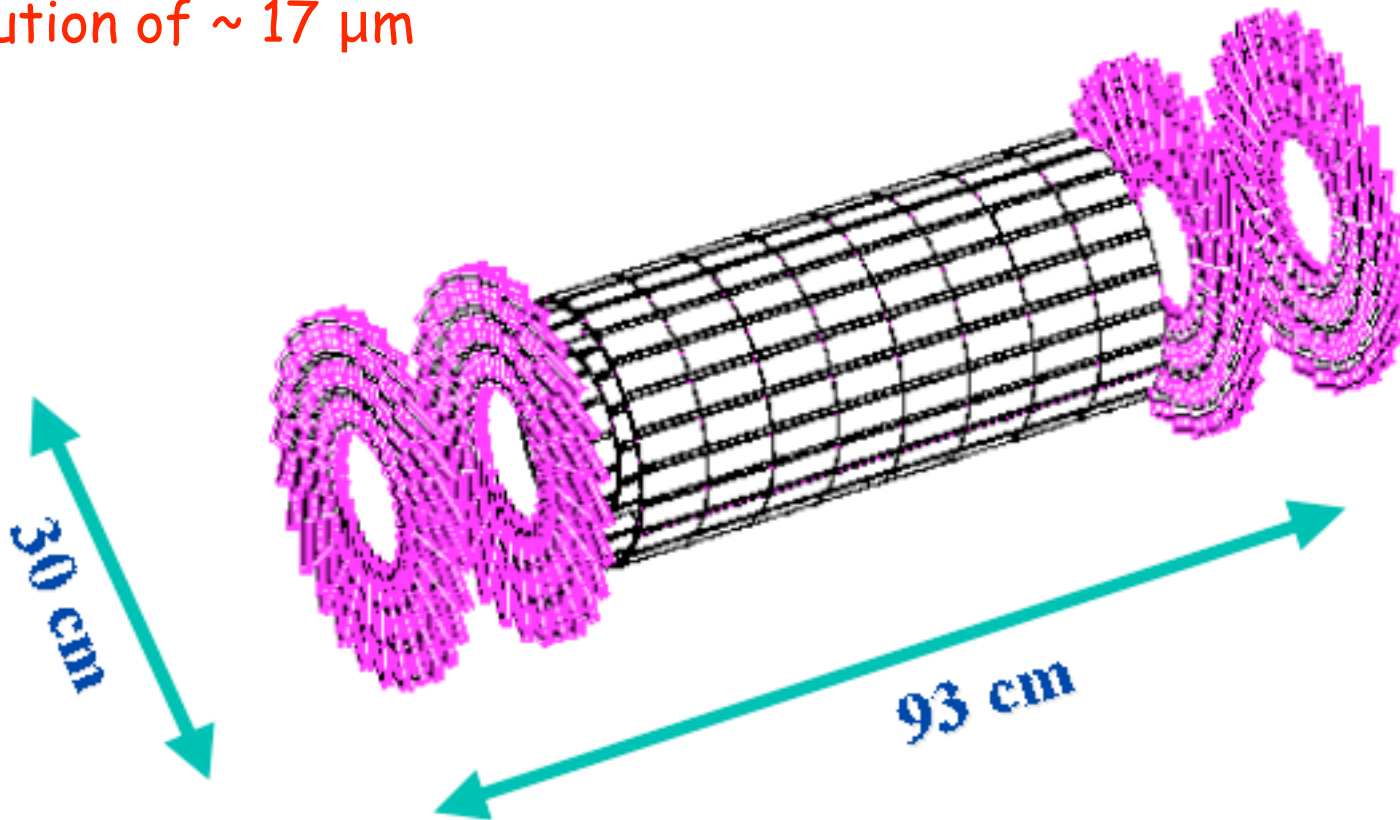


black is total of expected hits vs  $\eta$ , red is thin double-sided hits, blue is thick double-sided, green is sum of double-sided hits

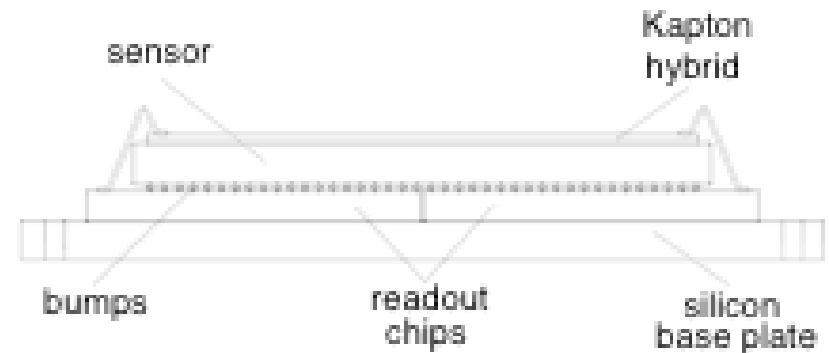
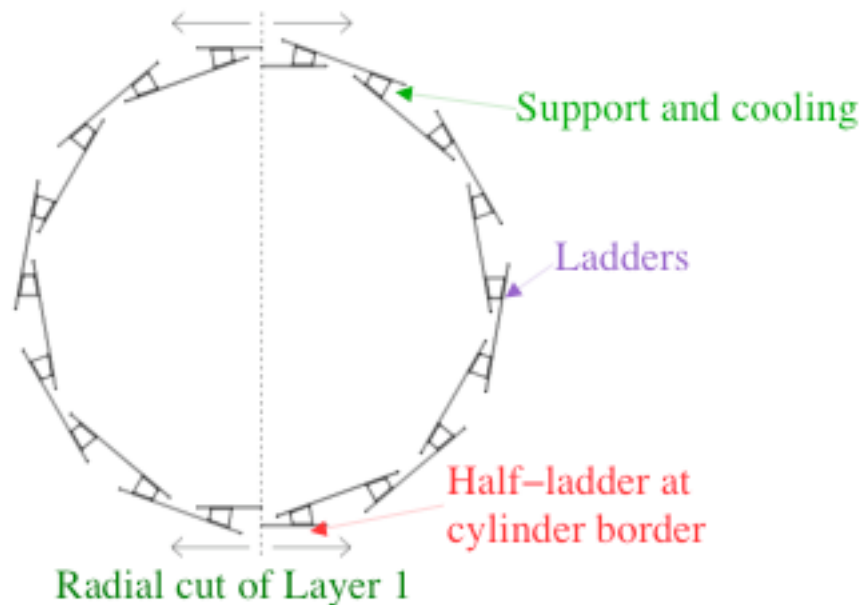


# The CMS Pixel Detectors

- 3 barrel layers at  $r \sim 4.4, 7.3, \text{ and } 10.2 \text{ cm}$ . Length of 53 cm
- Endcap disks at  $\pm 34.5 \text{ cm}, \pm 46.5 \text{ cm}$
- Pixel size of  $\sim 100 \mu\text{m} \times 150 \mu\text{m}$ . 48M pixels in barrel, 18M pixels in endcaps
- 3 high resolution space-points for  $\eta < 2.2$ , 2 for  $\eta < 2.8$   
r- $\phi$  resolution of  $\sim 10 \mu\text{m}$  (Lorentz angle of  $23^\circ$  for barrel pixels)  
r-z resolution of  $\sim 17 \mu\text{m}$



# Barrel Pixels

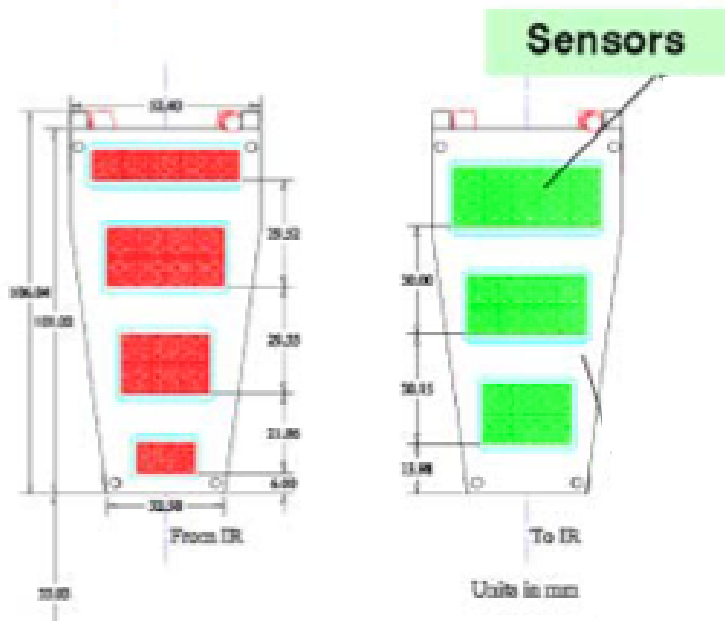


- Si sensors are 1.6 cm x 6.6 cm, 300  $\mu\text{m}$  thick
- 2x8 array of readout chips, Indium bump-bonded to sensors, form modules.
- Sensors have analog readout - analog-coded row/column, pixel pulse height. Shaping time  $\sim 25$  ns (1 bunch x-ing)
- 8 modules per ladder; 800 modules in barrel detector
- 2 data links/module in layers 1 and 2, 1 data link/module in layer 3
- Carbon Fiber support structure with cooling channels

# Forward Pixels

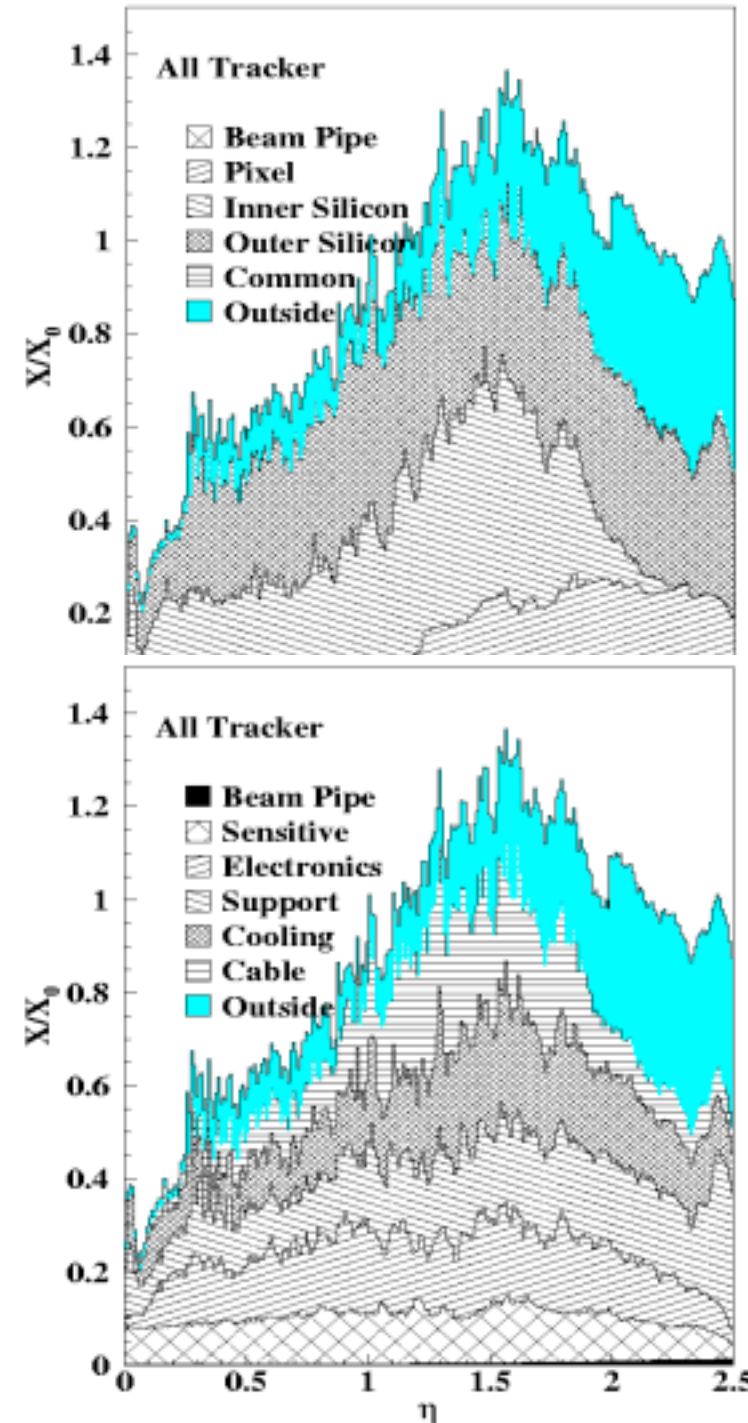


- Each forward disk consists of 24 blades
- Blades rotated by  $20^\circ$  for charge sharing (Lorentz angle, track inclination)
- 7 detector modules per blade (4 on front, 3 on back of blade)
- 45 readout chips per blade
- Room for another disk at  $z = 58.5$  cm ( $2.0 < \eta < 3.0$ ) if needed
- Both Barrel and Forward Pixel full detector assemblies expected to be installed for 2008 LHC Physics Run



# Reconstruction Considerations

- Detector has lots of granularity to deal with occupancy from tracks "not of physics interest" (min-bias pile-up, loopers, out-of-time, back-splash)
- Also has lots of material ( $\mu^\pm$  scatter,  $e^\pm$  scatter and bremsstrahlung,  $h^\pm$  scatter and interact!). Kalman Filter final track fit accounts for scattering and  $dE/dx$
- Interaction lengths have similar distribution as radiation lengths (right).  
Peak of  $\lambda/\lambda_0 \sim 0.45$  at  $\eta \sim 1.6$
- In many ways more difficult to deal with - radically alters/kills tracks (many hadrons don't get to outer layer of strip tracker)



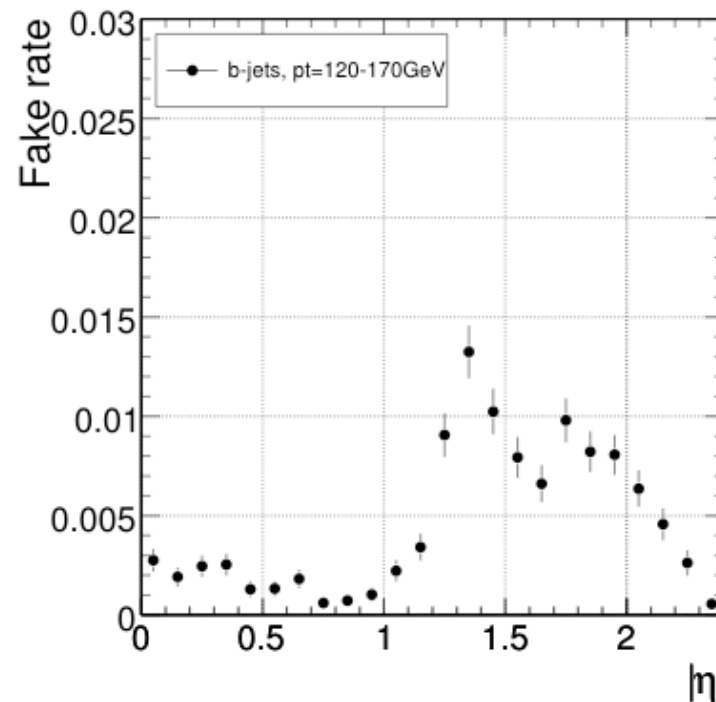
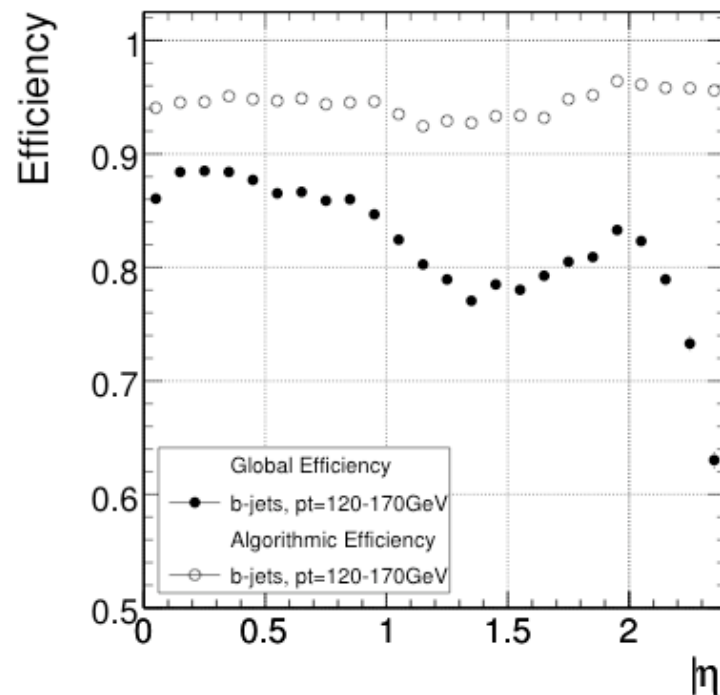
# Track Reconstruction Software

- Primary Pattern Recognition the Combinatorial Track Finder (CTF)
- Seeded from hit pairs in 2 pixel detector layers within acceptable windows. Even though most hits, pixels have lowest occupancy and tracks haven't interacted/decayed yet
- Can tighten seeding by using primary vertex
- Trajectory building -> propagate seed to new (compatible) layer, update parameters and errors (Kalman) with all compatible hits (new trajectories)
  - also make new trajectory with "null" hit in case of inefficiency
- Propagate these trajectory candidates to next layer in parallel (avoid bias)
- Trajectories killed if  $\chi^2$  too big or too many missing hits
- Final trajectories are Kalman fits of tracks - smooth with parameters of trajectory propagated backwards



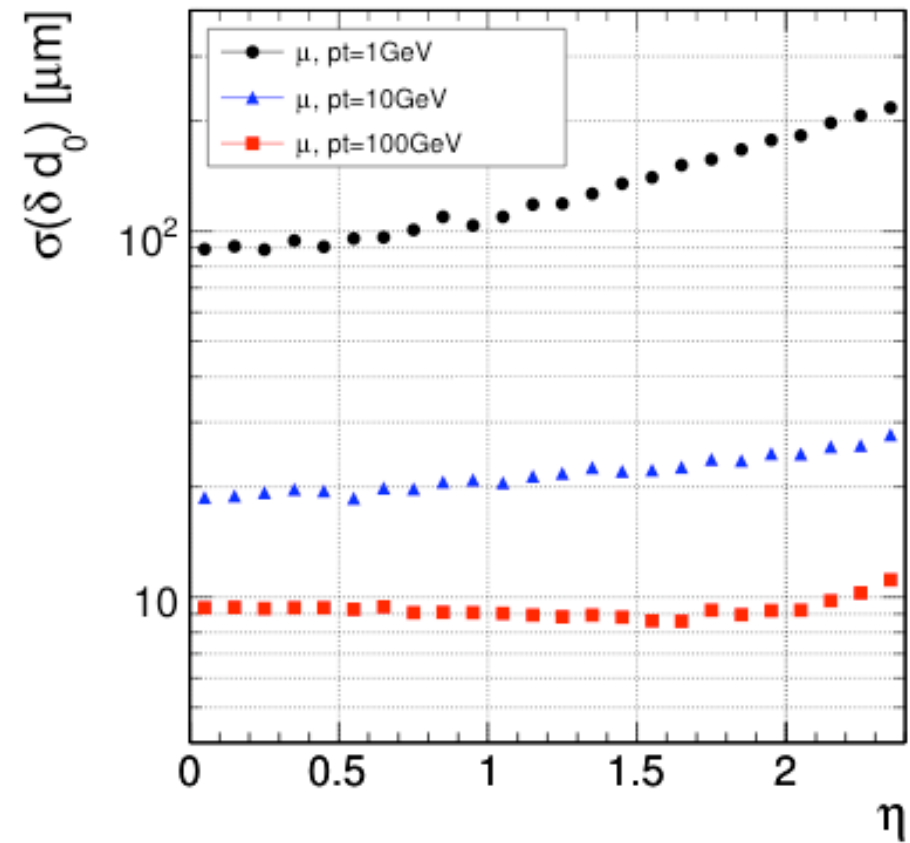
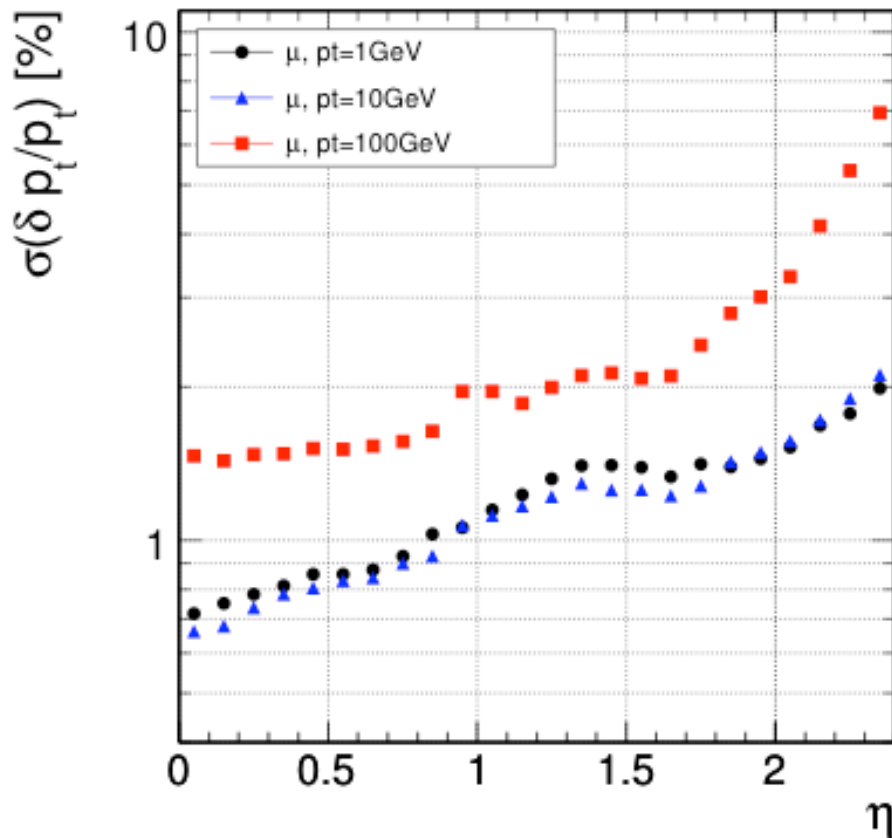
# Track Efficiency and Fake Rate

- CTF has been CMS standard tracking code for >5 years now; constantly being improved and extended
- Most of its time is spent in trajectory building
- Global efficiency  $\geq 99\%$  for high  $p_T$   $\mu$  with  $\eta < 2.0$
- Below left is global and algorithmic (fraction of tracks algorithm should find) efficiency for a hard case - tracks in high  $p_T$  (120-170 GeV) b jets with low luminosity pile-up added
- Right is fake rate for tracks in these jets



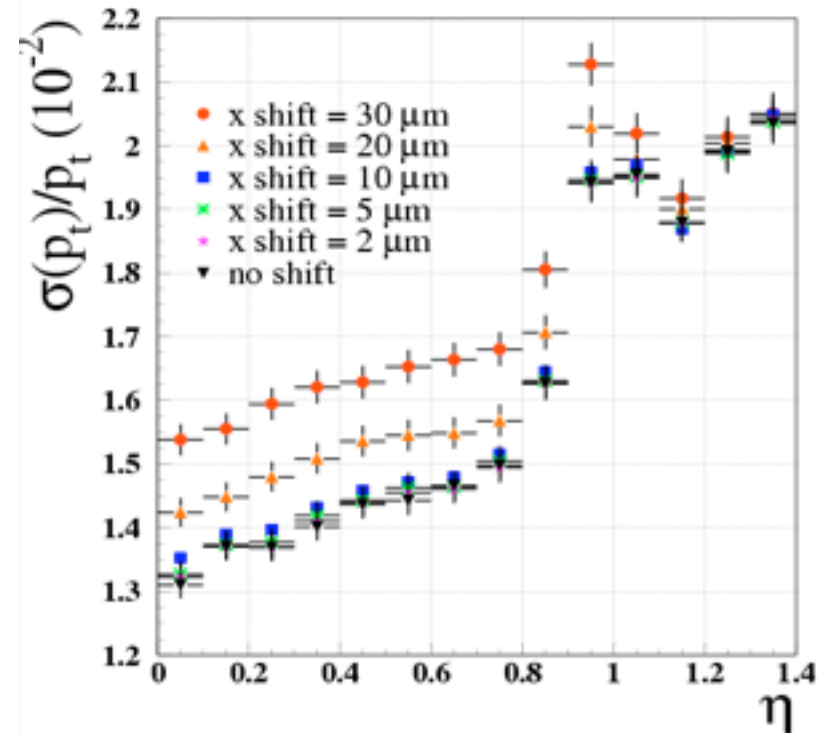
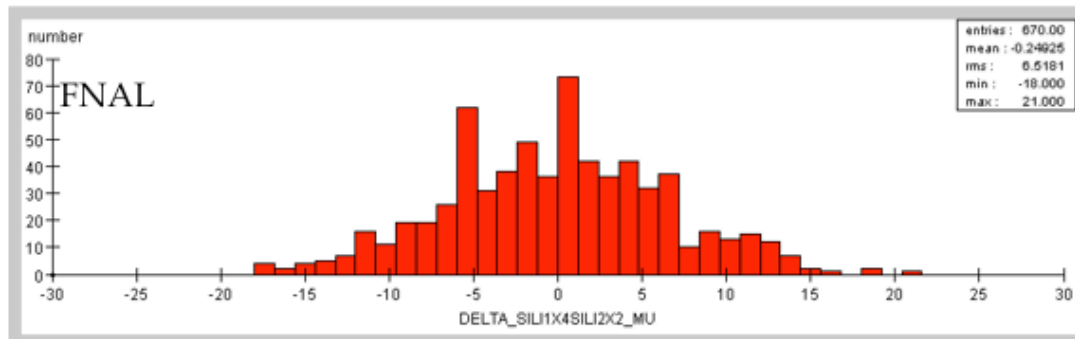
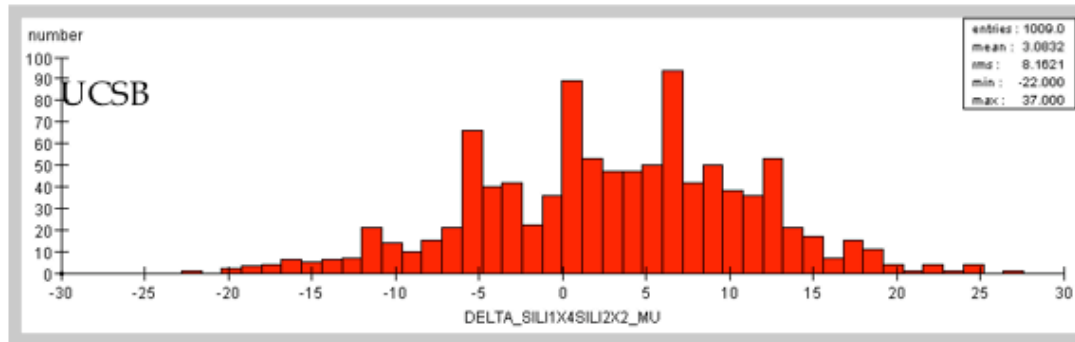
# Track Parameter Resolutions

- The combined trackers provide  $\sim 2\%$  or better  $p_T$  resolution for  $p_T = 100$  GeV/c tracks out to  $\eta \sim 1.25$  (better for lower  $p_T$ )
- For  $p_T = 10$  GeV/c tracks:
  - $\sigma(d_0) < 25 \mu\text{m}$  out to  $\eta = 1.5$ ;  $\sim 30 \mu\text{m}$  at  $\eta = 2.4$
  - $\sigma(z_0) < 60 \mu\text{m}$  out to  $\eta = 1.5$ ;  $\sim 150 \mu\text{m}$  at  $\eta = 2.4$



# Alignment Requirements

- Wafer positions carefully measured at all stages of assembly. Below left are  $x$  ( $\mu\text{m}$ ) of sensors in TOB modules -  $\sigma < 10 \mu\text{m}$
- This level of misalignment wouldn't even be seen in  $p_T$  resolution if left uncorrected (below right), but 2 or 3 times this would
- Sensor global placement to  $\sim 100 \mu\text{m}$  at the beginning - will need track-based alignment to get it down to  $\sim 10 \mu\text{m}$
- There is a laser system (LAS) for hardware alignment of the strip detectors - will monitor long-term shifts of large structures after the detector is assembled

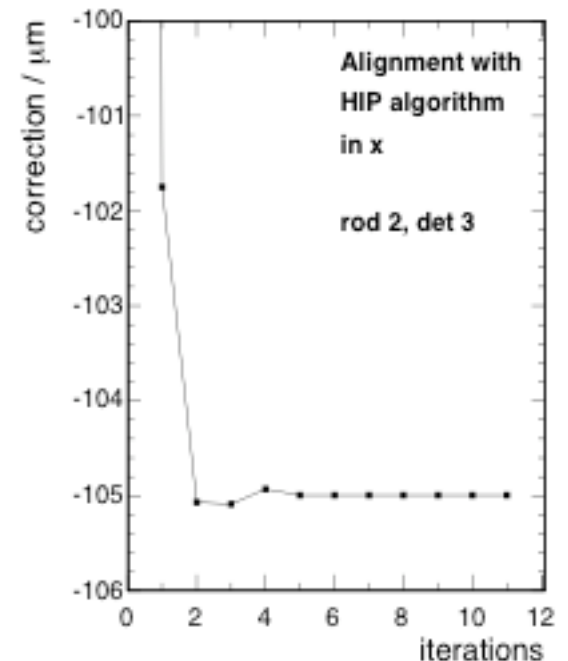
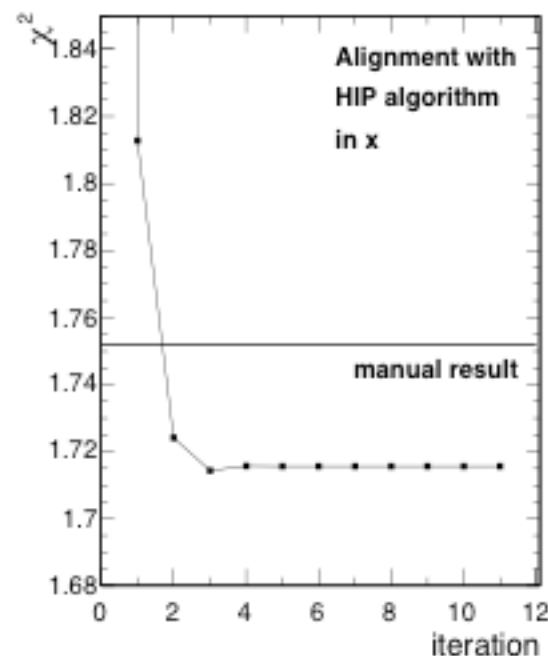
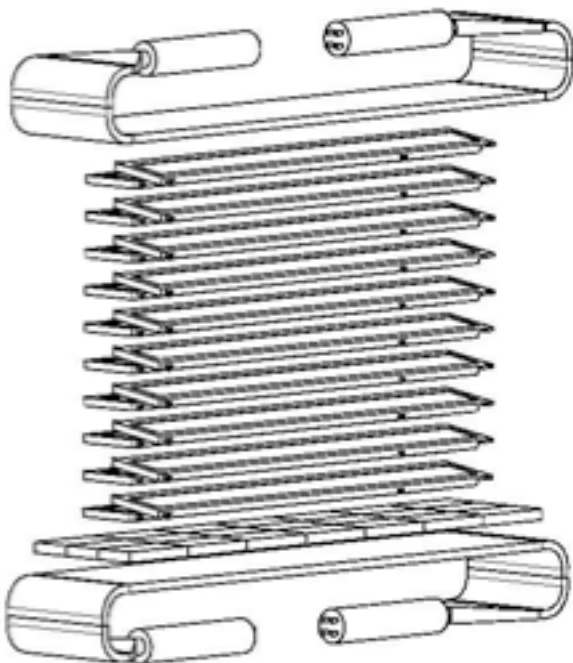


# Alignment Algorithms

- CTF shown to work well with misalignments up to 1 mm at low luminosity -> this is the starting point for track-based alignment of lots of modules (~20k including pixels)
- Several different track-based alignment algorithms currently being developed:
  - **HIP**: Hits and Impact Points collected for each alignable sensor. Analytic functions describe residuals for up to 6 alignment parameters/module ( $\chi^2$  min of 6N parameters). Inverts block diagonal matrix
  - **Millepede**: Fits to 6N + track parameters simultaneously. Inverts very large matrices. New version ~ ×1000 faster than previous, adapted to run on O(10k) rank matrices
  - **Kalman Filter**: update alignment params after every track; correlations without inversion of large matrices
  - **Simulated Annealing**

# Alignment Tests with Cosmic Rack

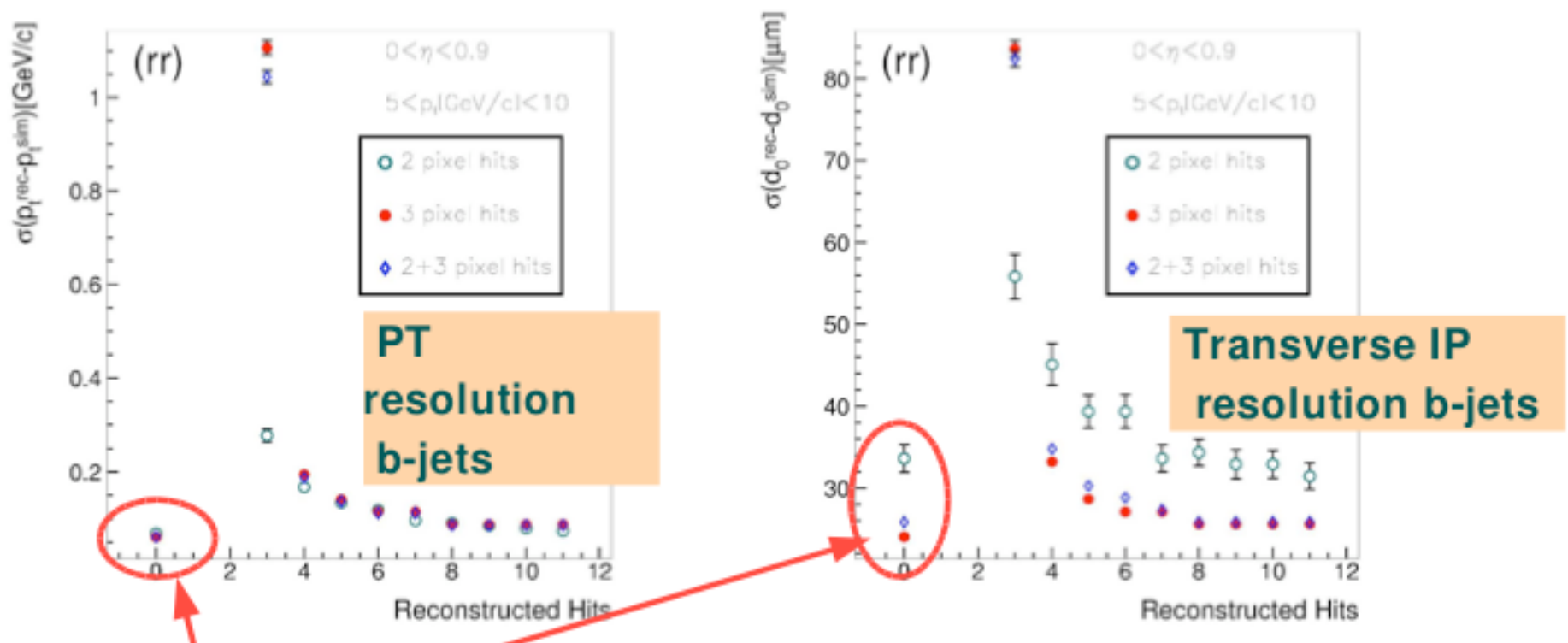
- The CRack is a test-stand for RODs which mimics a wedge of the TOB (Sept 2004 test-beam run) or more (see below left) - also a cosmic telescope
- CRack tracks (reco-ed using a modified CTF and identical software alignment elements) provide some tests of alignment algorithms
- Easily aligned manually. HIP, aligning in x only, produces better results and converges quickly (x and yaw only marginally better)
- Millepede applied to same data produces consistent results





# Fast Track Reconstruction

- Can use CTF seed finding, trajectory building, and fitting code in High-Level Trigger (HLT)
- Full tracking too slow but can stop as soon as parameters get good enough for trigger purposes (truncate trajectory building, where most tracking time spent). ~5-6 hits usually enough

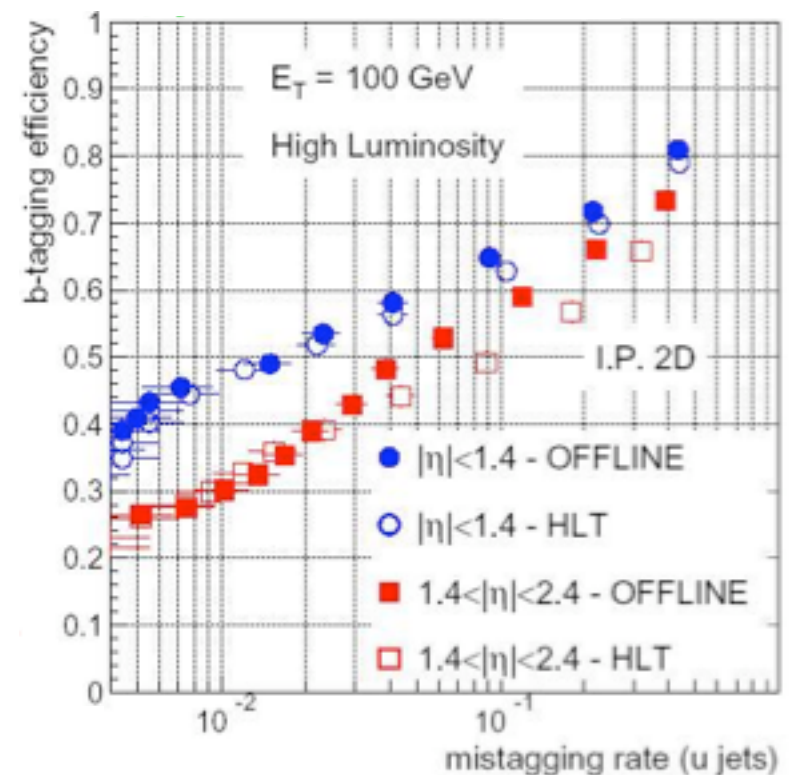


Tracking results with all possible hits included

# Impact Parameter b Tagging

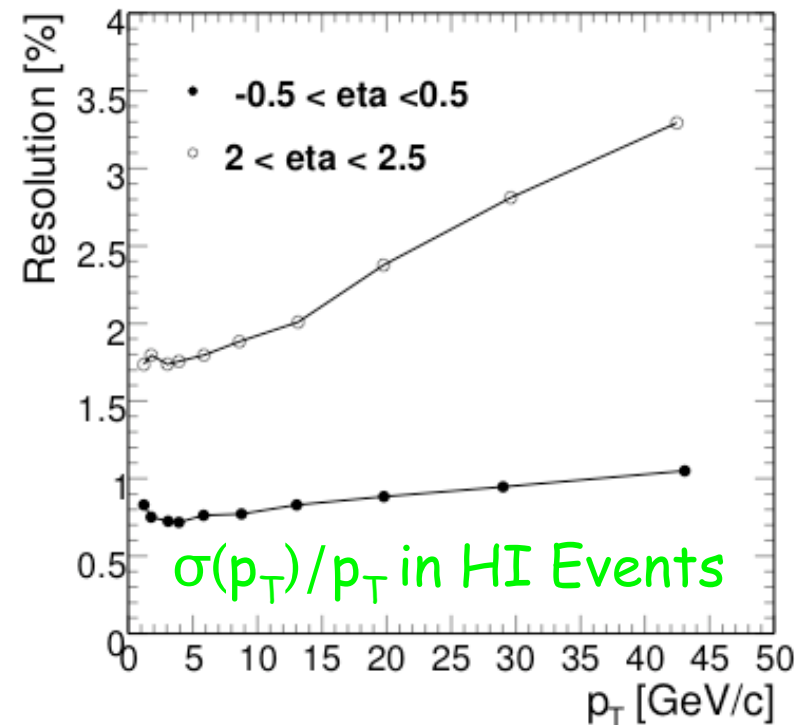
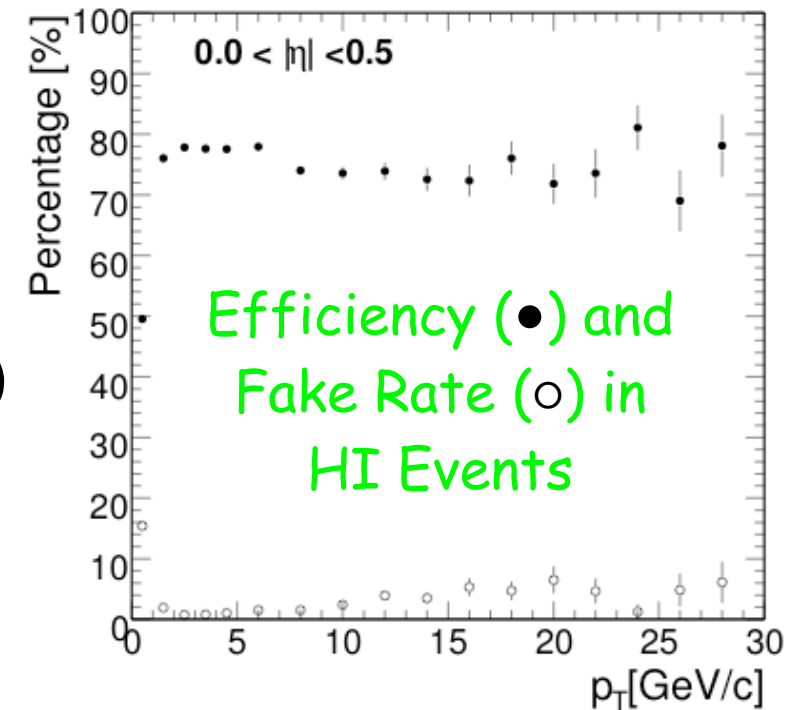
- If combined with regional tracking (looking for tracks only in a region defined by trigger lepton or jet) can consider doing b-tagging in HLT with fast partial tracking
- Performance with partial tracking run out to 7 hits (open symbols) not much worse than that for full offline tracking (solid symbols) for simple impact parameter b-tag
- This will really rely on having the alignment under control

b-tag eff vs mistag rate for u-jets for regional, partial (7 hit) tracking.  
Tag: 2 trks with  $IP/\sigma > \text{cut}$



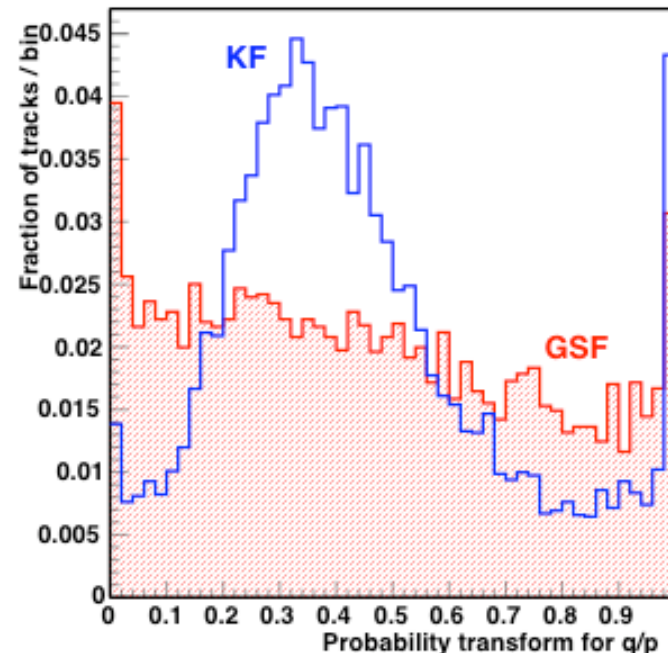
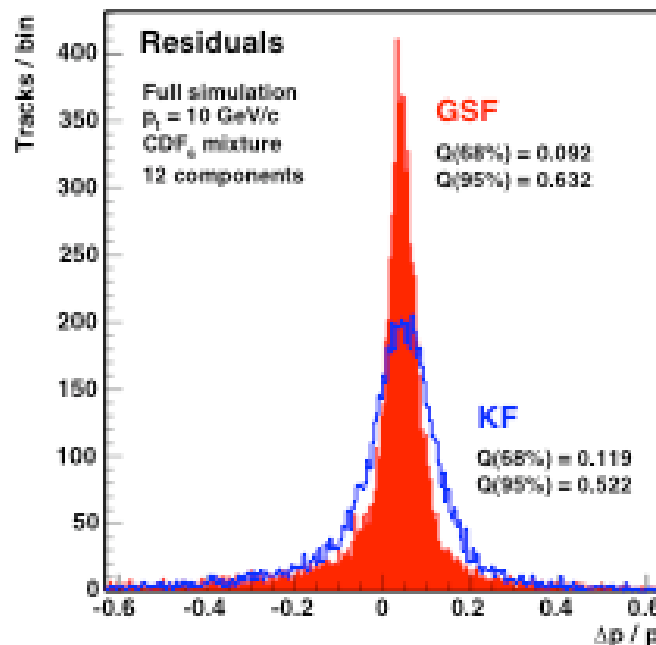
# Heavy Ion Tracking Performance

- In central PbPb Events we expect very high track densities:
  - $dN/dy_{\text{PbPb}} \sim 3500$  ( $dN/dy_{\text{pp}} \sim 7$ )
  - HI tracking must be robust at high occupancy ( $\sim 1\%$  in pixels, up to 50% in strips)
- Specialized HI tracking algorithm:
  - Seed tracks with pixel triplets (low occupancy, good initial estimate of track parameters)
  - Use Kalman Filter to propagate tracks into strips. Special error assignment for merged hits
  - Select only one track per seed by best  $X^2$
  - Perform final fit with stereo layers "split"
  - To reject fakes, require  $> 12$  hits (out of 17),  $P(X^2) > 0.01$ ,  $d_0/\sigma > 3$
- Excellent performance even at highest track densities



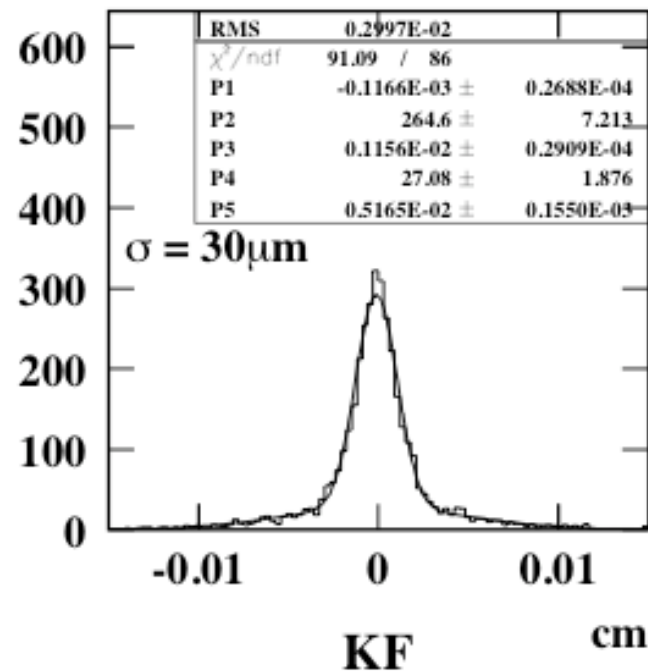
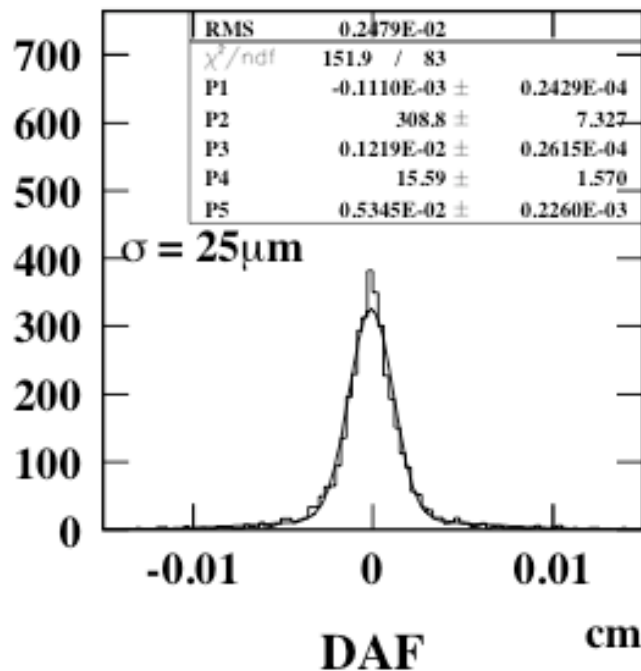
# Gaussian Sum Filter

- In Kalman Filter (KF) multiple scattering and Energy loss variance are (well) treated as Gaussian “process noise”
- Some processes, like bremsstrahlung, are inherently non-Gaussian (Bethe-Heitler) but can be approximated as a sum-of-Gaussians
- Introduce new components (multiplication of # of states). After each update recalculate weights (non-linear). Retain only high probability components (in plot limited to 12)
- Increases fit time by (unoptimized) factor of  $\sim 200$ . Use only on  $e^\pm$  candidates of interest. But also significantly improves parameters, pulls



# Deterministic Annealing Filter

- Assignment of wrong hit in pattern recognition causes tails in parameter distributions; right hit is often close-by
- DAF (equivalent to "Elastic Arms") allows multiple hits/layer to be assigned to a track. Competing hits assigned (normalized) probabilities based on residual to track
- KF fitter/smoothen run to convergence; recalculate probabilities (non-linear)
- Also "anneal" fit while converging ( $V \rightarrow \alpha V$ ,  $\alpha = 81 \rightarrow 1$ ) to keep out of local minima. Below is transverse impact param ( $d_0$ ) for  $p_T > 15$  GeV tracks in high  $E_T$  b jets. Also flattens  $P(X^2)$  distributions

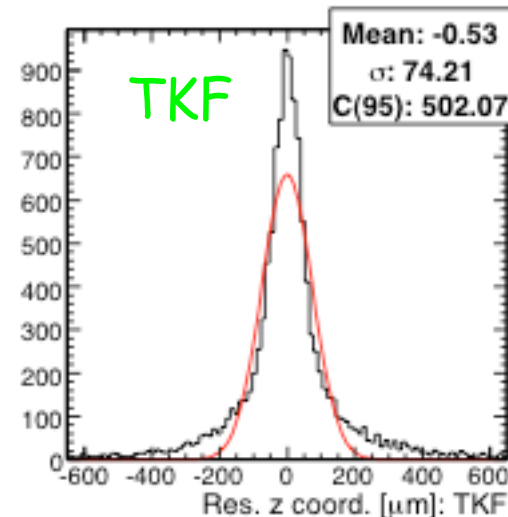
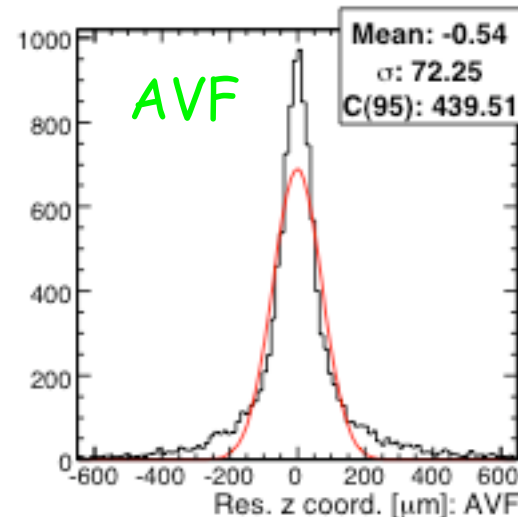
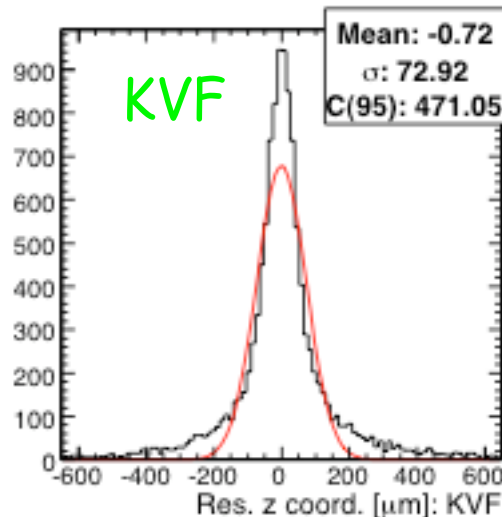




# Vertex Fitting Algorithms

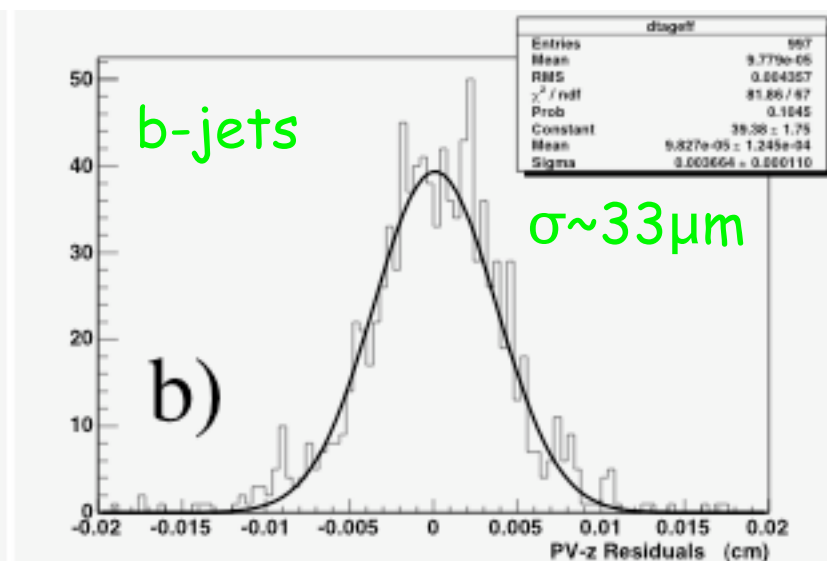
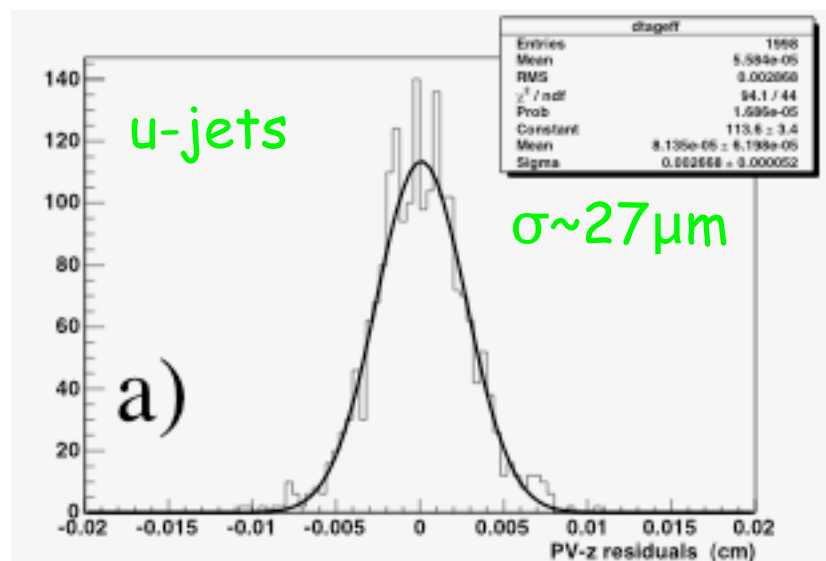
- Several different vertex fitting algorithms being investigated:
  - Kalman Vertex Fitter - The standard. Linear. Refit of track with vertex constraint. But sensitive to tails on track param resolutions and tracks not from vertex
  - Trimmed Kalman Fitter - discards tracks with  $< 5\%$  (typical) probability of coming from vertex
  - Adaptive Vertex Fitter - iterative KF where tracks are weighted by  $w(d/\sigma, T)$ .  $T$  changes with iteration (anneals)
  - Gaussian Sum Vertex Fit - add mixture of Gaussians to track error distributions (for tails)

$z(\text{fit}) - z(\text{true})$   
Bs  $\rightarrow$   $\psi\phi$  vertex  
fit



# Primary Vertex Finding

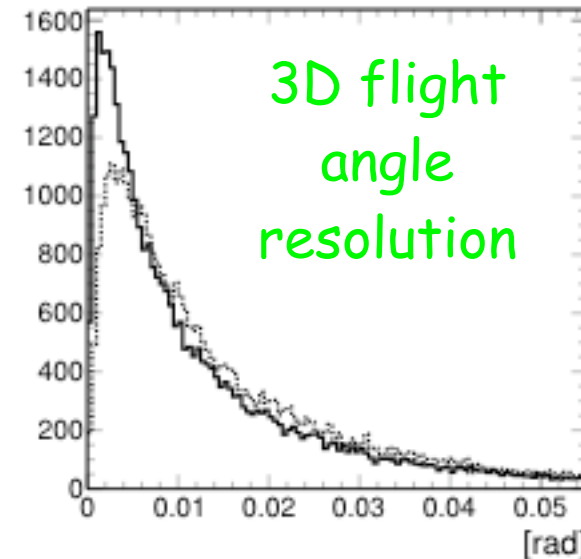
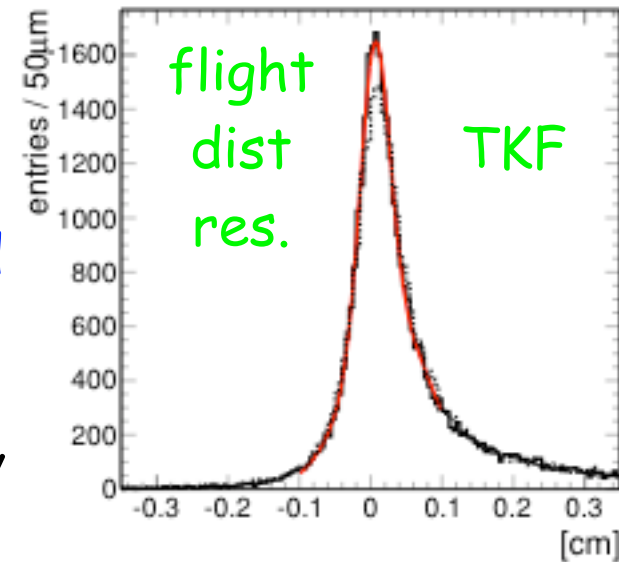
- Primary vertexing moves from off-line into HLT so information available there and for seeding full tracking
- A tighter variant of fast tracking uses triplets of hits in the pixel detectors only
- After cuts on  $p_T$  and impact parameter, vertices are formed using a histogramming method (z impact parameter) or a variant of Trimmed KF
- Trimmed KF shows slightly better results. Efficiencies ~80-100% for various physics processes (low multiplicity like  $H \rightarrow \Upsilon\Upsilon$  harder)
- Typical  $z_{PV}$  resolutions at low luminosity shown below. Results consistent with PV reconstruction with full tracking



# Jet Vertex b Tagging

- Two vertex algorithms have been studied for finding secondary vertices (b, c decays) - the Trimmed Kalman Vertex Fitter (TKF) and a Tertiary Vertex Finder (TVF)
- TVF based on Kalman but uses tracks from tertiary (b→c) that might otherwise be trimmed away from secondary vertex
- Also some tertiary tracks assigned to secondary vertex (and bias reconstructed vertex forward) now have another place to go
- With typical secondary vtx cuts ( $L/\sigma > 3$ , away from PV and beampipe, mass cuts), have ~63% eff for 90% purity with TKF (resolutions at right) for 20-70 GeV  $p_T$  b-jets in barrel, slightly higher with TVF

Also investigated effect of short-term misalignment (dashes)



# Conclusions

- The strip tracker is entering final assembly stage. The pixel detectors appear on-schedule for 2008 LHC Physics run
- Various early tracker subsystems beginning to take cosmics. The Magnet Test/Cosmic Challenge should start seeing cosmics in (very limited) tracker with full field soon
- The main tracker pattern recognition (CTF) and Kalman final fit are quite robust and adaptable:
  - It can be used with less than the full detector for speed (for the HLT) and produces quality results
  - With modifications it can handle the  $dN/dy \sim 3500$  of HI interactions
  - It can be adapted to deal with complex, non-Gaussian processes and resolution tails in track fitting and vertexing
- The tracking and vertexing code is being ported to a new, more modular event data structure (CMSSW). The basic functionality is there now, ready for validation. Now need to port higher-level code (like GSF - easier) and resume developing
- The CMS tracking system is beginning to come together in a hurry!